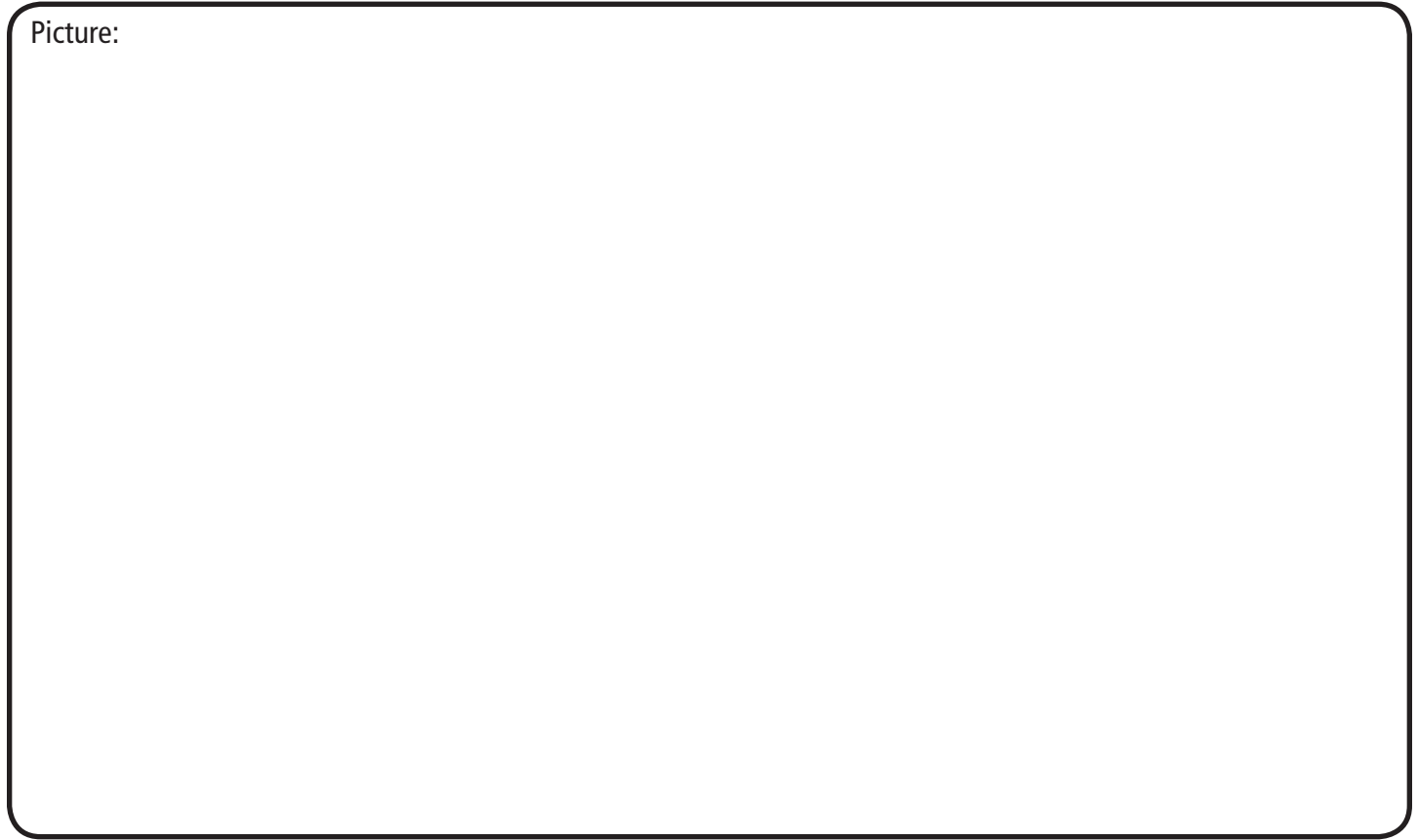


# ROBOT DESIGN

Robot's Name:

Picture:



## PERFORMANCE:

Wheel Circumference

**Distance per rotation:**

Straight Line Test

**Distance from center after 10 feet:**

**Distance from center after 20 feet:**

Turning Test

degrees

accuracy out of 5 tries

**90° turn**

**5 4 3 2 1**

**180° turn**

**5 4 3 2 1**

**360° turn**

**5 4 3 2 1**

Modifications or  
Special Features:

